

The first result of the morphological coupling of the breaking wave model

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Motivation

Coastal erosion is a worldwide issue



Understand sediment transport mechanism and the wave dynamic



Beach at Biscarrosse, Southwestern France

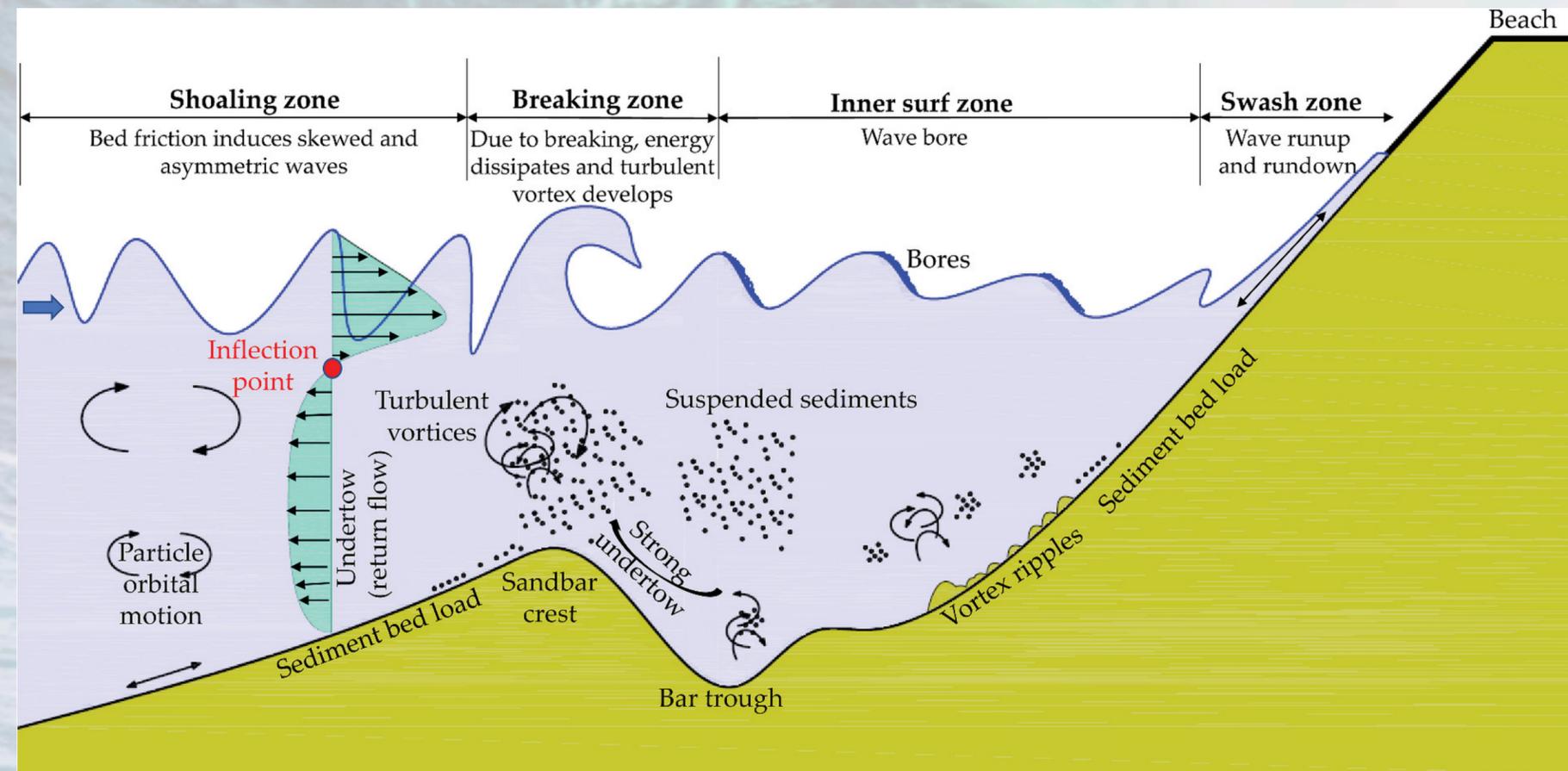


The beach on Tainan's Golden Coast, Taiwan, disappeared

Adapted from: [Le monde: By 2100, coastal erosion will have affected thousands of buildings in France](#)
[Taiwan: Saving the disappearing coastline](#)

Near-shore wave dynamic

- In shoaling zone, asymmetric wave
- In breaking zone, turbulence is generated and large amounts of energy are released



↓
Entrain sediment into the fluid

- Undertow transports sediment in the off-shore direction

modeling breaking wave
becomes a priority before
studying sediment transport

Elsayed, S. M., et al. (2022) "Nonhydrostatic numerical modeling of fixed and mobile barred beaches: Limitations of depth-averaged wave resolving models around sandbars."

Outline

1. Breaking wave model
 - Model derivation and analysis
 - Numerical validation
2. Morphodynamic coupling
 - Numerical scheme
 - LIP experiment

Depth-averaged model

Navier-Stokes equation

- ✓ Full resolution of the interior of fluid
- ✗ Computational costly

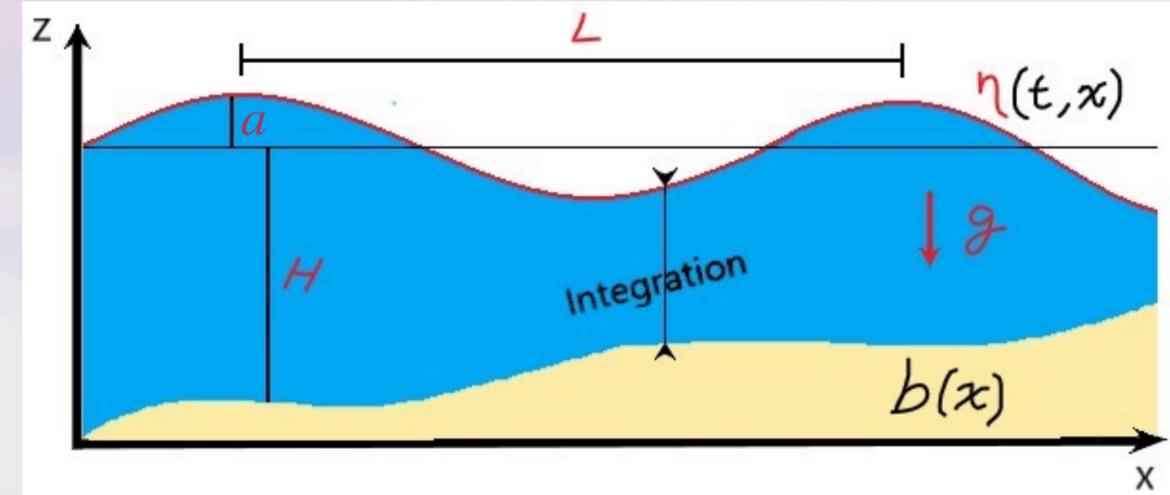
- Integrating over the depth
- Asymptotic analysis

$$\frac{\partial h}{\partial t} + \text{div}(h\mathbf{U}) = 0$$

Mass eq.

$$\frac{\partial h\mathbf{U}}{\partial t} + \text{div} \left(h\mathbf{U} \otimes \mathbf{U} + \frac{gh^2}{2} \mathbf{I} + p_N \right) = 0$$

Momentum eq.



$$\delta = (H/L)^2 \quad (\text{Shallowness/dispersion})$$

$$\varepsilon = a/H \quad (\text{Nonlinearity})$$

$$\dot{h} = \frac{Dh}{Dt} = \frac{\partial h}{\partial t} + U \frac{\partial h}{\partial x}, \quad \ddot{h} = \frac{D^2 h}{Dt^2}$$

model	NSWE $O(\delta)$	SGN $O(\delta^2)$
Pressure	$p_N = 0$	$p_N = h^2 \ddot{h} / 3$
Type	Hyperbolic	Dispersive

Breaking wave : Energy dissipation

Classic models do not take breaking into account.

Their derivation within a conservative framework



no natural energy
dissipation mechanisms
due to wave breaking

Classic methods are:

- Extra terms in the mass and/or the momentum equation to provide a necessary dissipation.
- Switching or hybrid methods (natural dissipation through the shock)

Recent approach is to use the **enstrophy** (Teshukov, 2007)
Richard & Gavriluk, **2015**;
Gavriluk, Chesnokov & Liapidevskii, **2016**

Outline

1. Breaking wave model

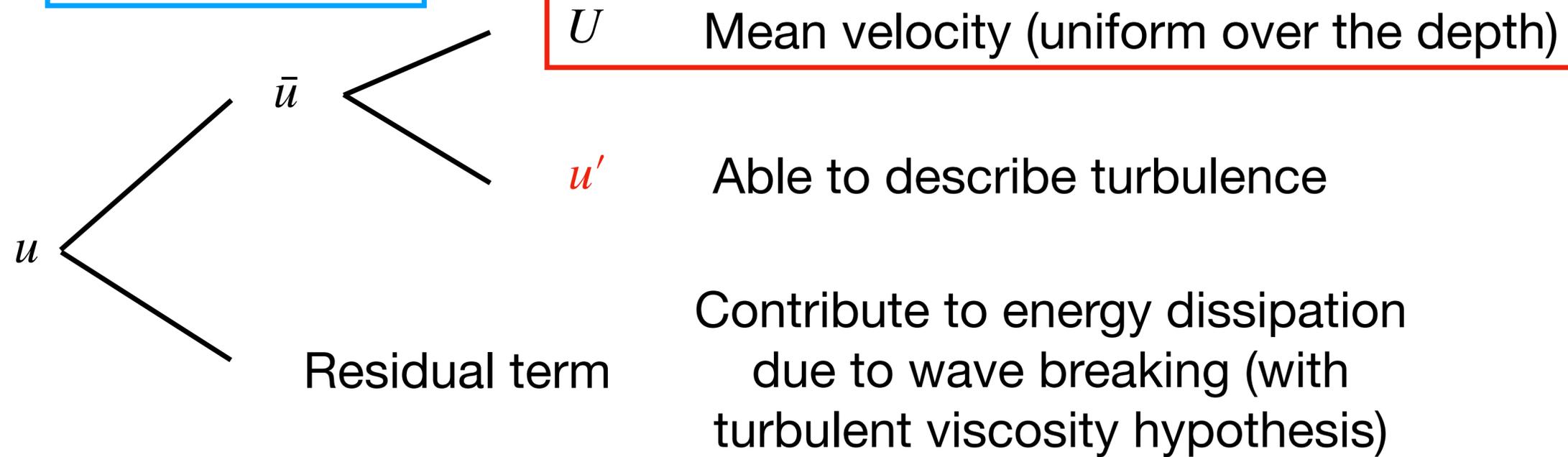
- Model derivation and analysis
- Numerical validation

2. Morphodynamic coupling

- Numerical scheme
- LIP experiment

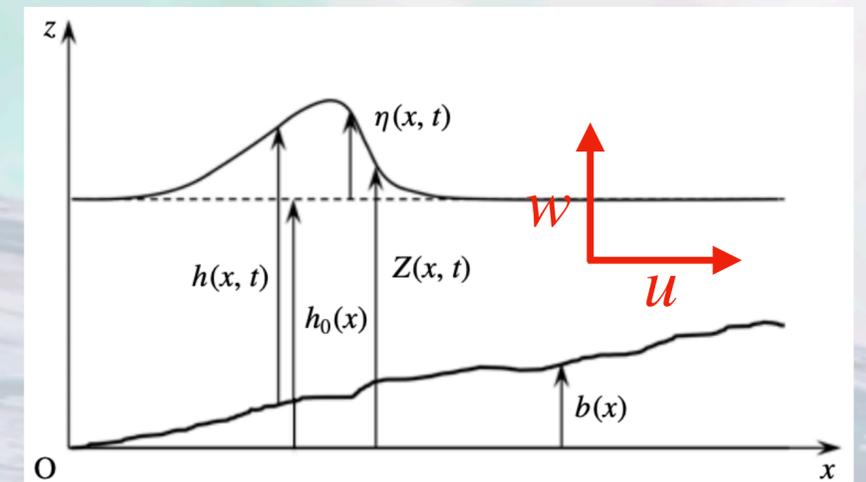
Model assumptions

About breaking



The assumption of both NSW and SGN model

Same assumption of the breaking wave model developed by Kazakova & Richard, **2019**



Breaking waves model

Model derivation

Dimensionless NS equations

- Depth-average
- Impermeable and no-slip BC
- Keep the terms up to $O(\delta^2)$

Enstrophy φ for evaluate vorticity magnitude

$$\text{Mech} \left(\int \text{eqs } dz \right)$$

Equation for φ

v.s.

$$\int \text{Mech}(\text{eqs}) dz$$

Equation for P

Hyperbolicity: every waves have finite speed.

Pseudo-compressibility

Internal (acoustic) energy e_a

$$\int \text{Mech.} + \text{acoustic } dz$$

v.s.

Equation for $\langle e_a \rangle$

Postulate $\langle e_a \rangle = \frac{P^2}{2a_c^2}$

Breaking waves model

Final dimensional equations under mild slope condition

$$\tilde{\varphi} := \frac{\langle \tilde{u}'^2 \rangle}{\tilde{h}^2} \equiv \frac{1}{\tilde{h}^3} \int_{\tilde{b}}^{\tilde{\eta}} \tilde{u}'^2 d\tilde{z}$$

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left(hU^2 + \frac{gh^2}{2} + h^3\varphi + hP \right) = \frac{\partial}{\partial x} \left(2\nu_T h \frac{\partial U}{\partial x} \right) - gh \frac{\partial b}{\partial x}$$

$$\frac{\partial hW}{\partial t} + \frac{\partial hUW}{\partial x} = \frac{3}{2}P + 3\nu_T \frac{\partial U}{\partial x}$$

$$\frac{\partial hP}{\partial t} + \frac{\partial hUP}{\partial x} = -a_c^2 \left(h \frac{\partial U}{\partial x} + 2W \right)$$

$$\frac{\partial h\varphi}{\partial t} + \frac{\partial hU\varphi}{\partial x} = -\frac{2}{h} \langle P^r \rangle + \frac{4\nu_T}{h} \left(\frac{\partial U}{\partial x} \right)^2 - \frac{8\nu_T W}{h^2} \frac{\partial U}{\partial x}$$

- The conservative part of the model is hyperbolic if $h > 0$
- Asymptotic dispersive properties to the SGN equation when $a_c \rightarrow \infty$

Outline

1. Breaking wave model

- Model derivation and analysis
- **Numerical validation**

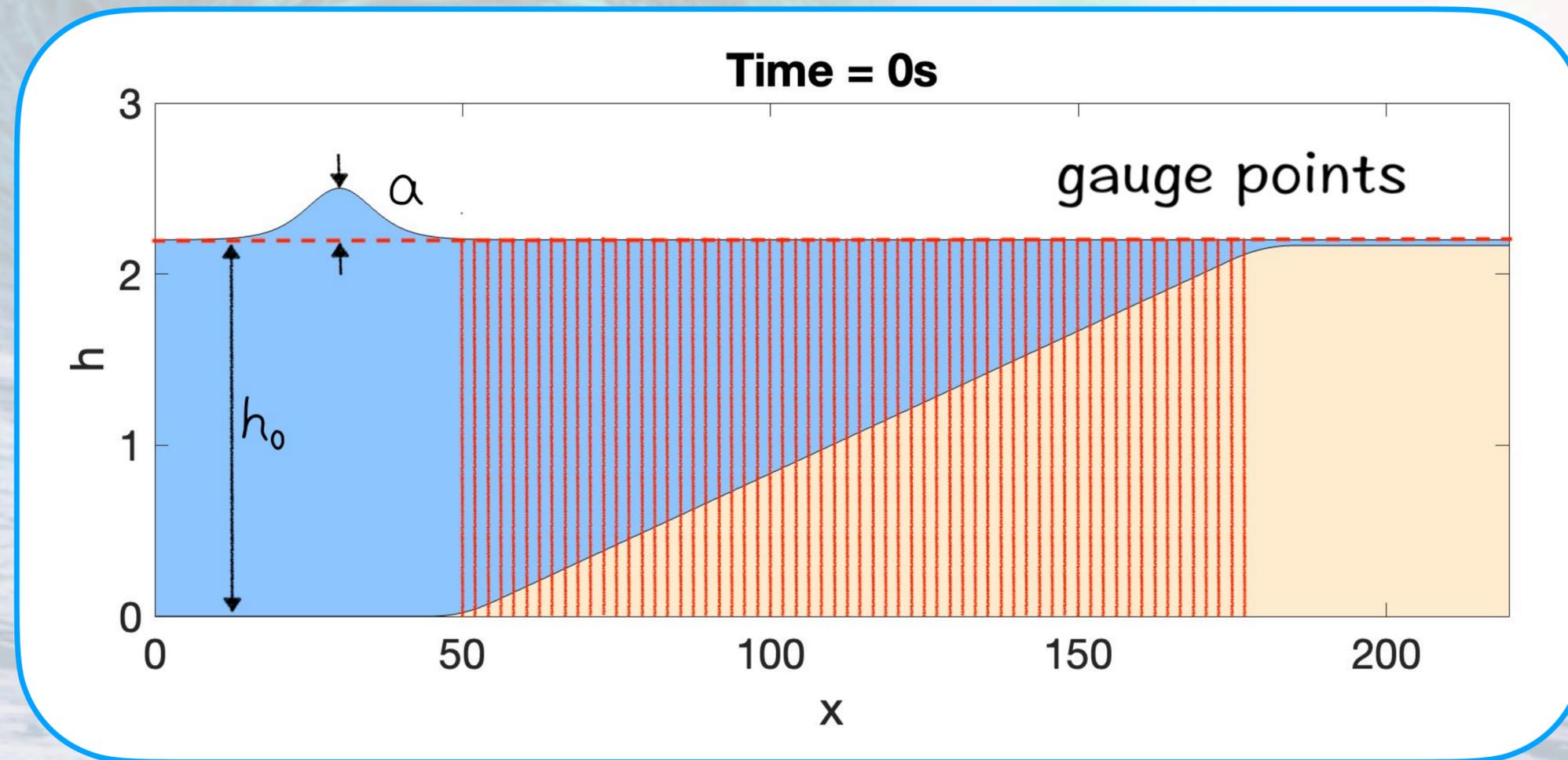
2. Morphodynamic coupling

- Numerical scheme
- LIP experiment

Numerical validation

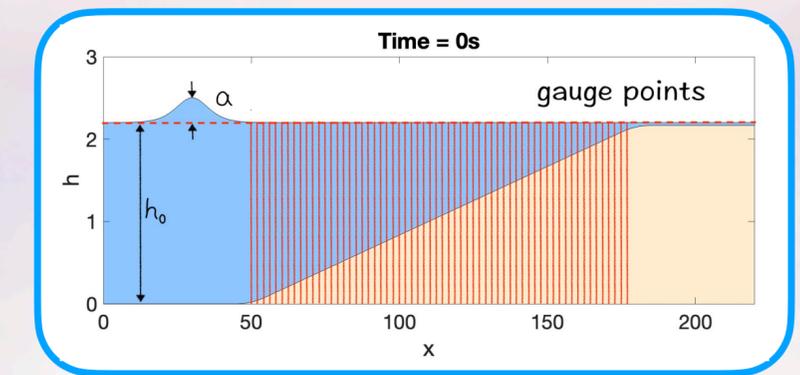
Experiment of Hsiao, 2008

Solitary waves with different water depths h_0 and non-linearities $\varepsilon = a/h_0$ propagate onto a slope with $\tan \beta = 1/60$



Numerical validation

Experiment of Hsiao, 2008; Gauge point comparison of Trial 25 & 41



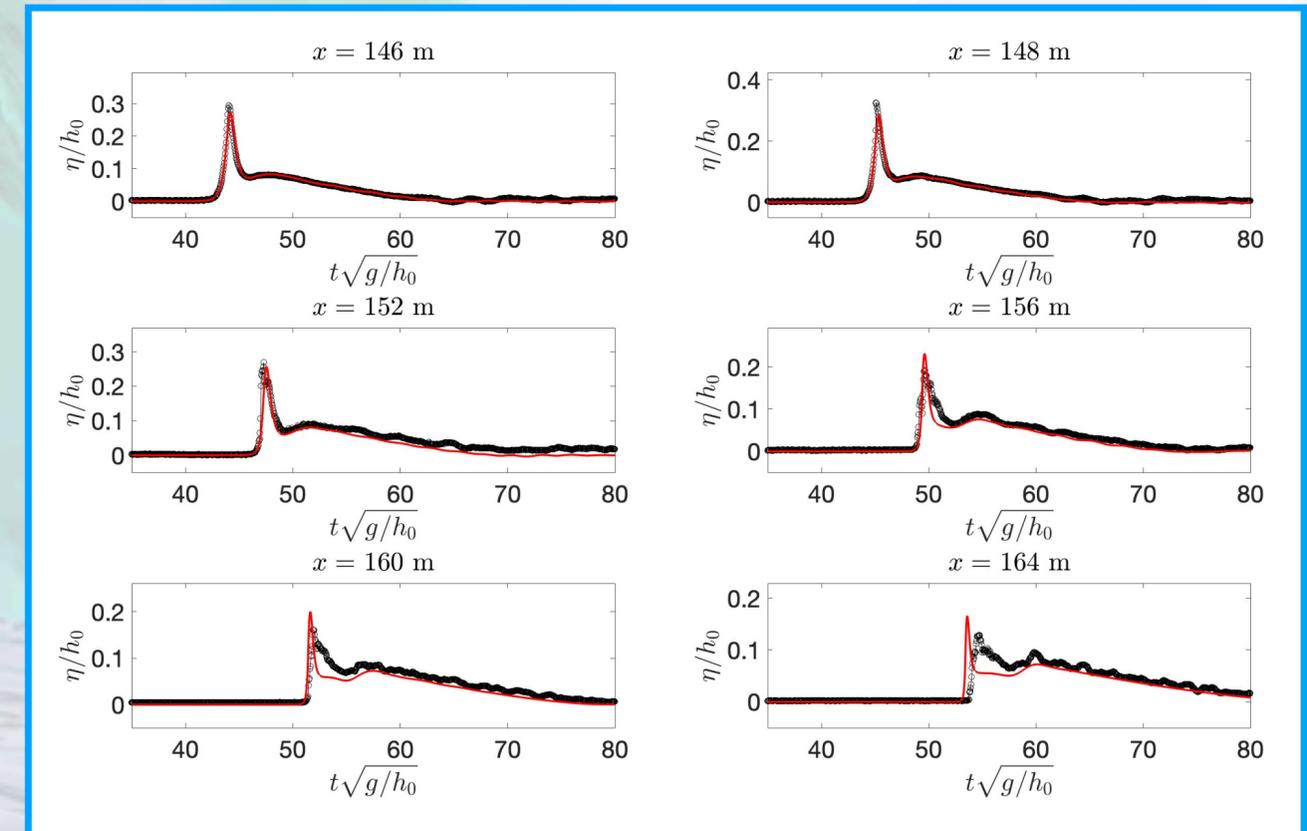
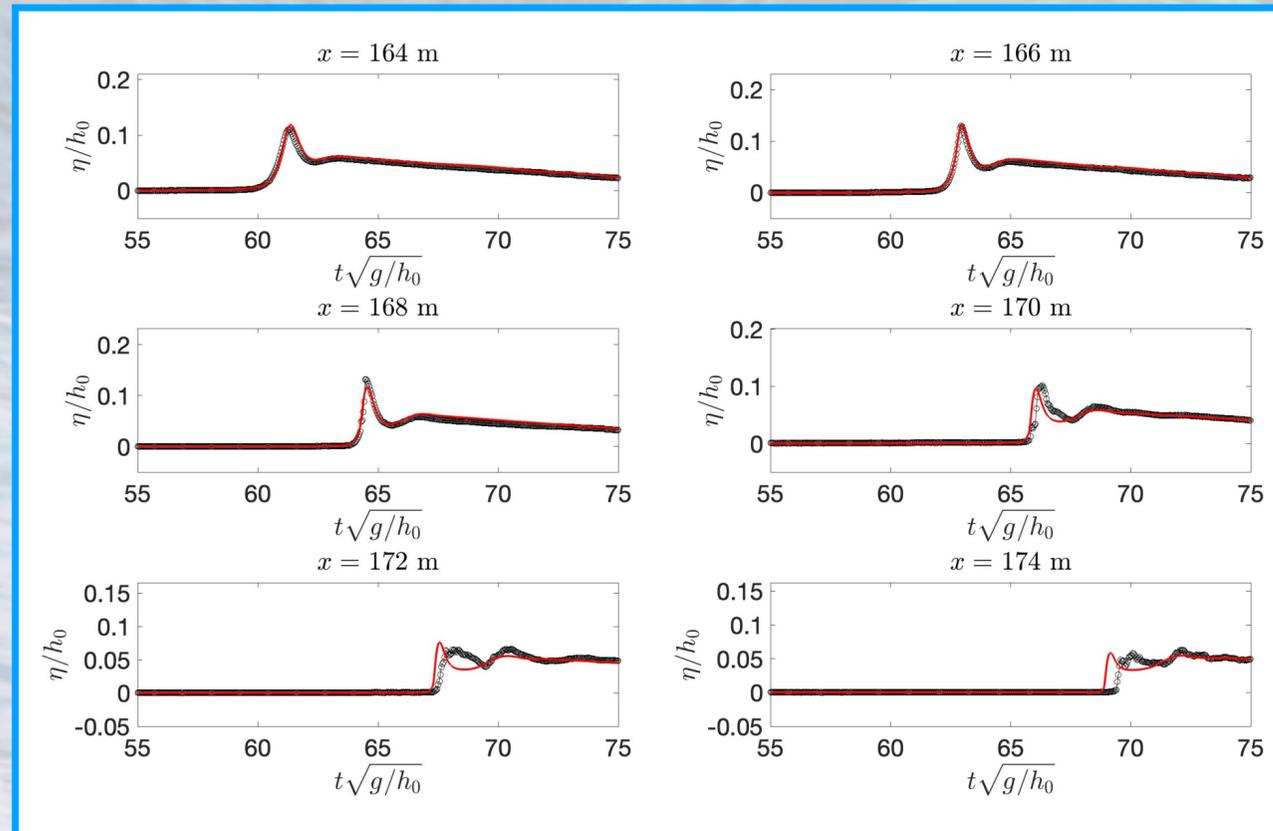
Trial 25
 $h_0 = 2.2$ m
 $\varepsilon = 0.054$

Breaking position:
 Real: 167 m
 Numerical: 166.7 m

Trial 41
 $h_0 = 2.2$ m
 $\varepsilon = 0.137$

Breaking position:
 Real: 148 m
 Numerical: 148.5 m

Amplitude

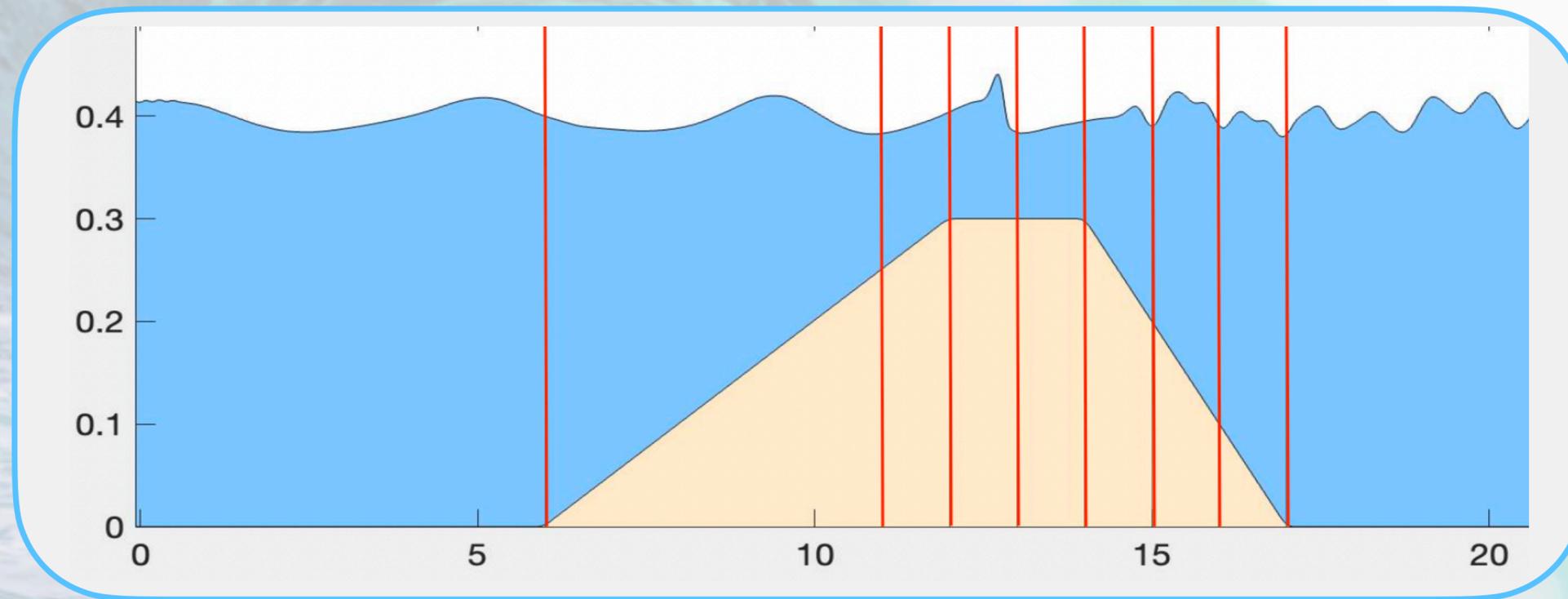


Time Series

Numerical validation

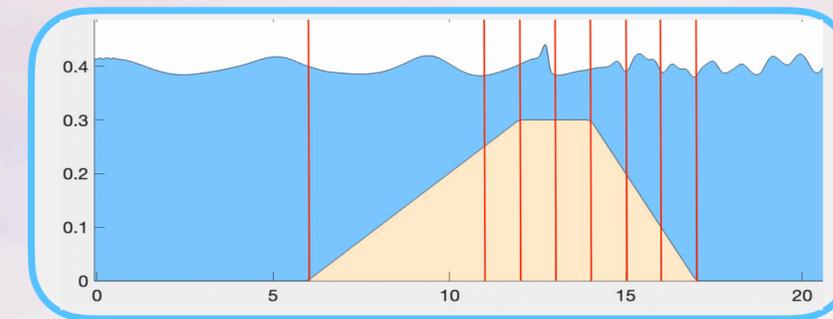
Experiment of Beji & Battjes, 1993

Regular and irregular wave trains with water depth $h_0 = 0.4$ m enter the domain from the left and propagate onto a submerged bar.

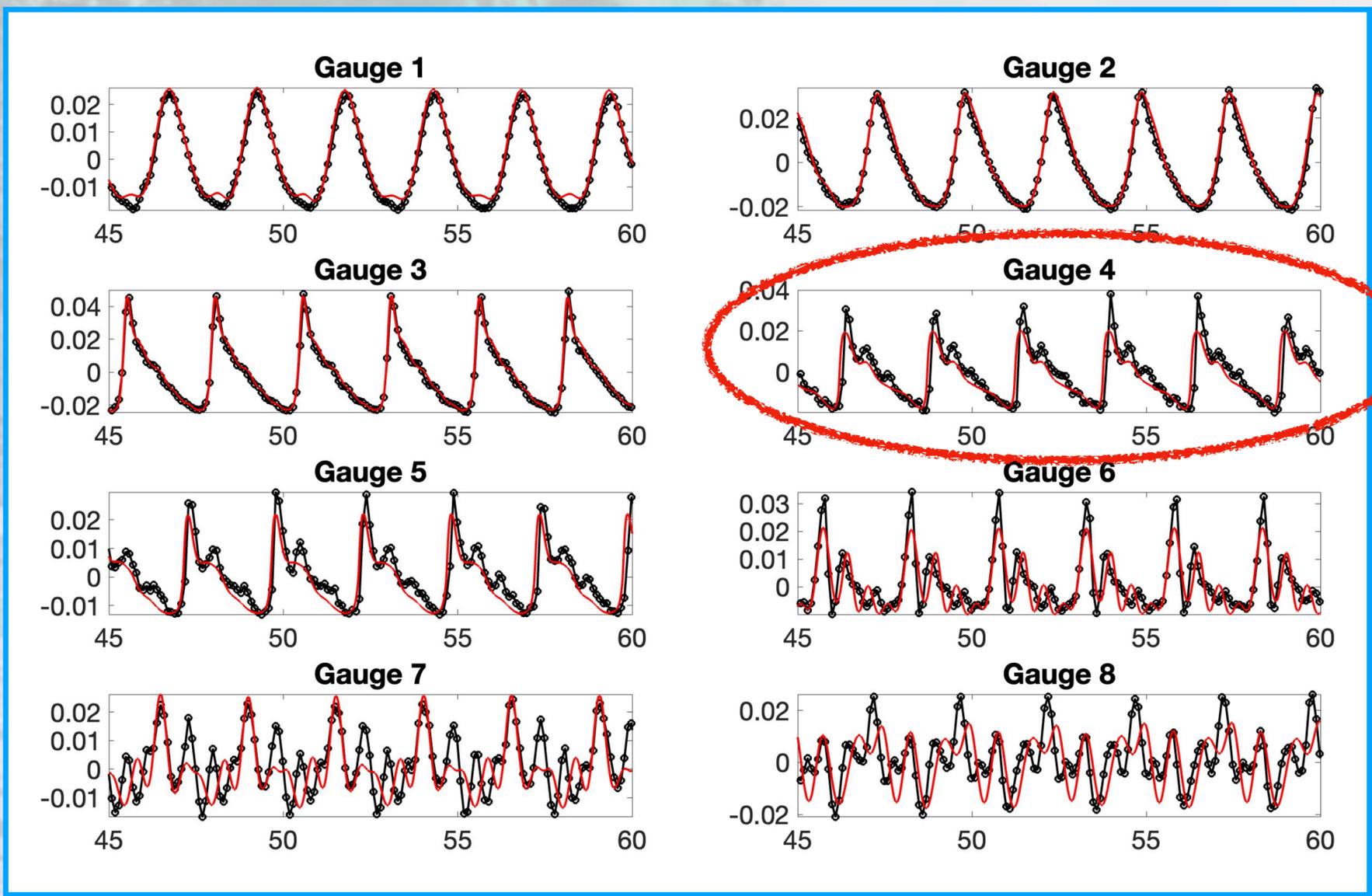


Numerical validation

Experiment of Beji & Battjes, 1993; Gauge point comparison



Amplitude



Time Series

True breaking position lies between gauge 3 and 4

Dispersive property can be improved for the regime with strong dispersive effect (Bonneton, 2011)

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Motivation



European **Large Installation Plan (LIP)** experiments was carried out in Delft Hydraulics's Delta Flume.

LIP experiment condition: 13h~18h

- **Marchesiello et. al., 2022; Shafiei et. al., 2023** use CROCO to run the LIP experiments
→ Does examine a long term simulation but being a 3D wave-resolving model
- **Mancini et. al., 2020** couple XBeach with sediment transport equations
→ Depth-averaged model but doesn't examine a long term simulation

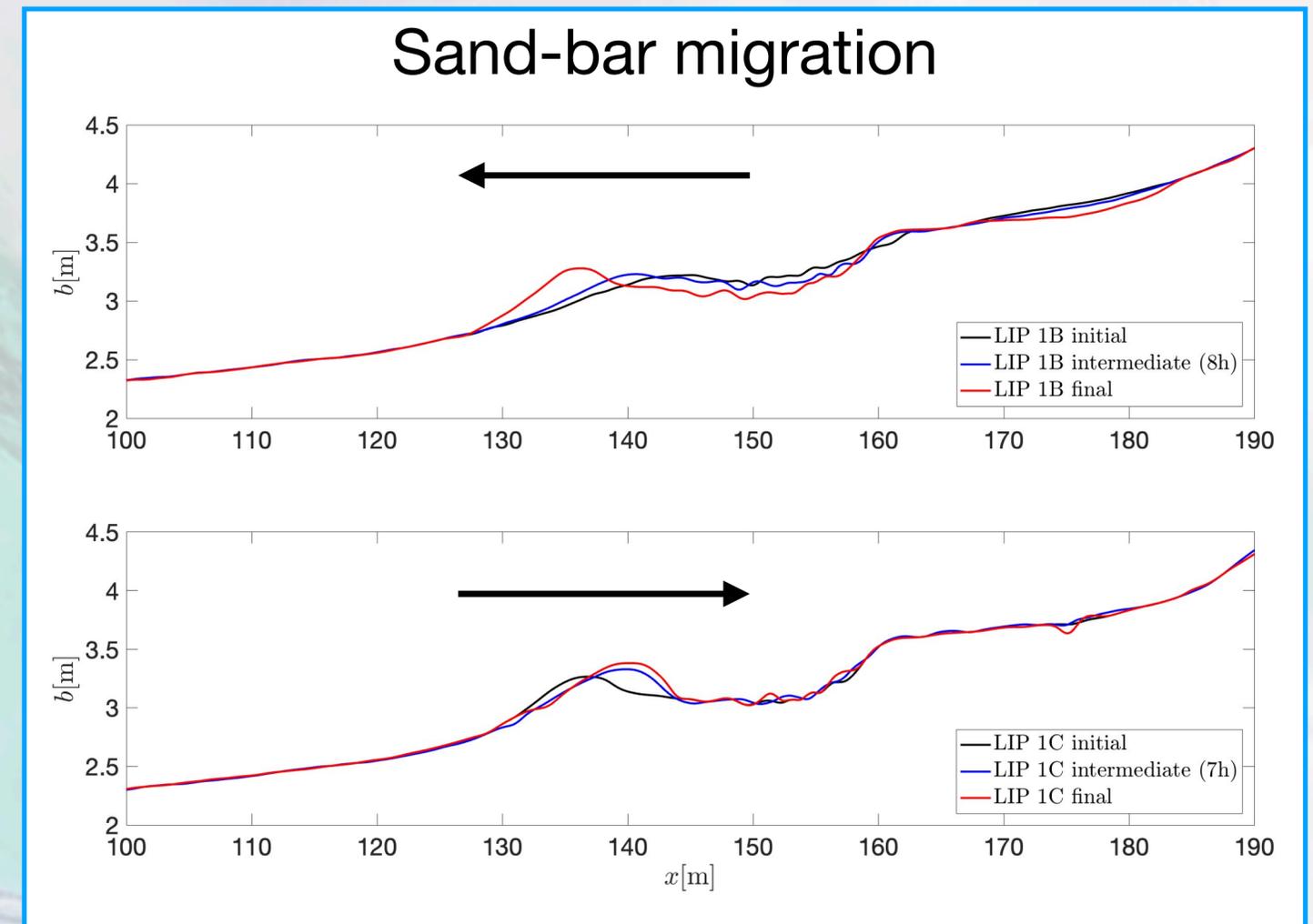
LIP Experiments

LIP-1B (More energetic)

- More energetic wave trains
- Effect of the suspended load dominant
- Create **undertow**
- Move sand-bar **away from** the shore

LIP-1C (Less energetic)

- Less energetic wave trains
- Effect of the bed load dominant
- Move sand-bar **toward** the shore



Goal: Does depth-averaged model capable to describe the undertow effect?

Morphodynamic equations

Equation for suspended-load (Concentration)

$$\frac{\partial hC}{\partial t} + \frac{\partial hUC}{\partial x} = E - D$$

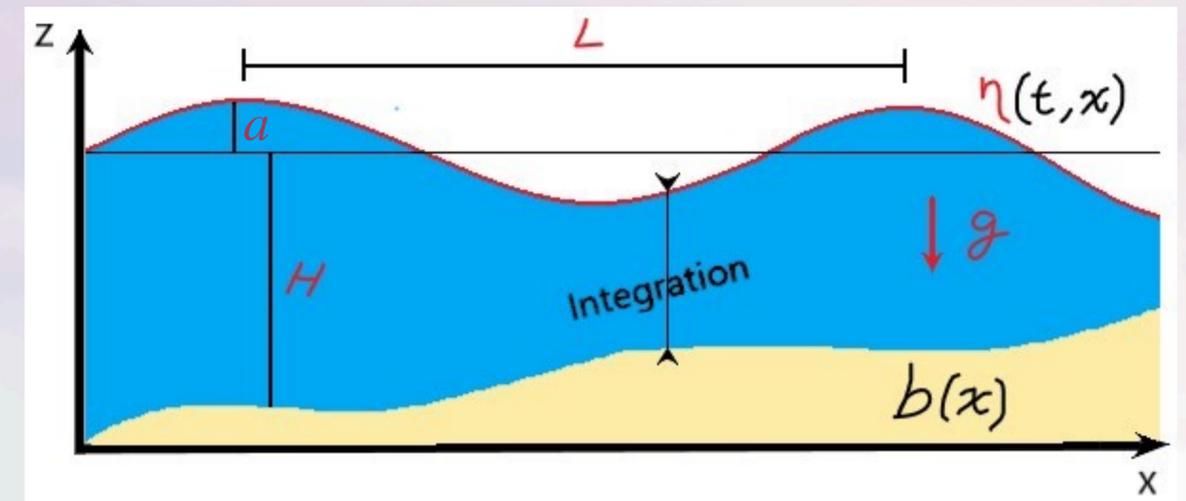
Equation for bed evolution (Exner-type)

$$\frac{\partial b}{\partial t} + \frac{\partial q_b}{\partial x} = D - E$$

- Simple
- Applicable in large scale sediment transport

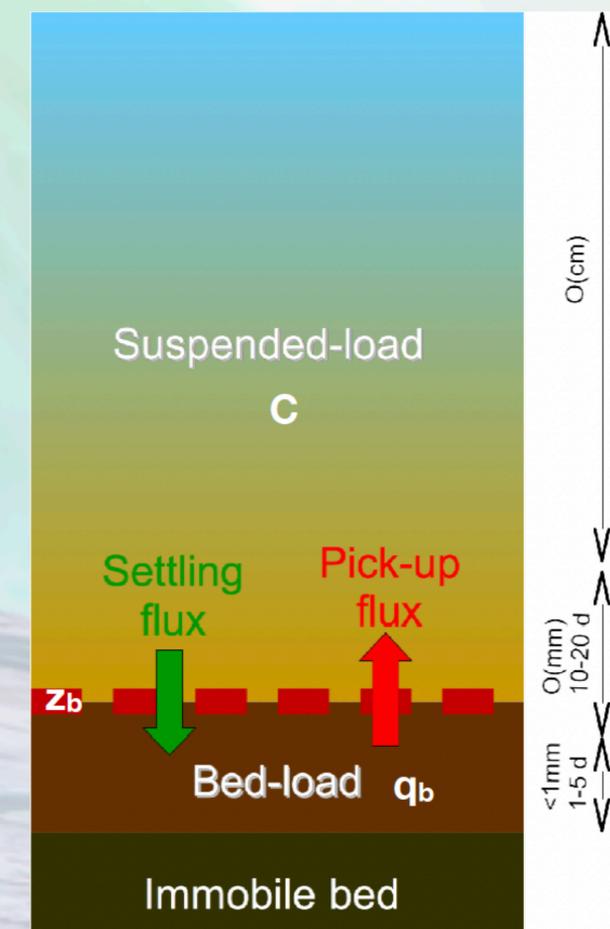
But

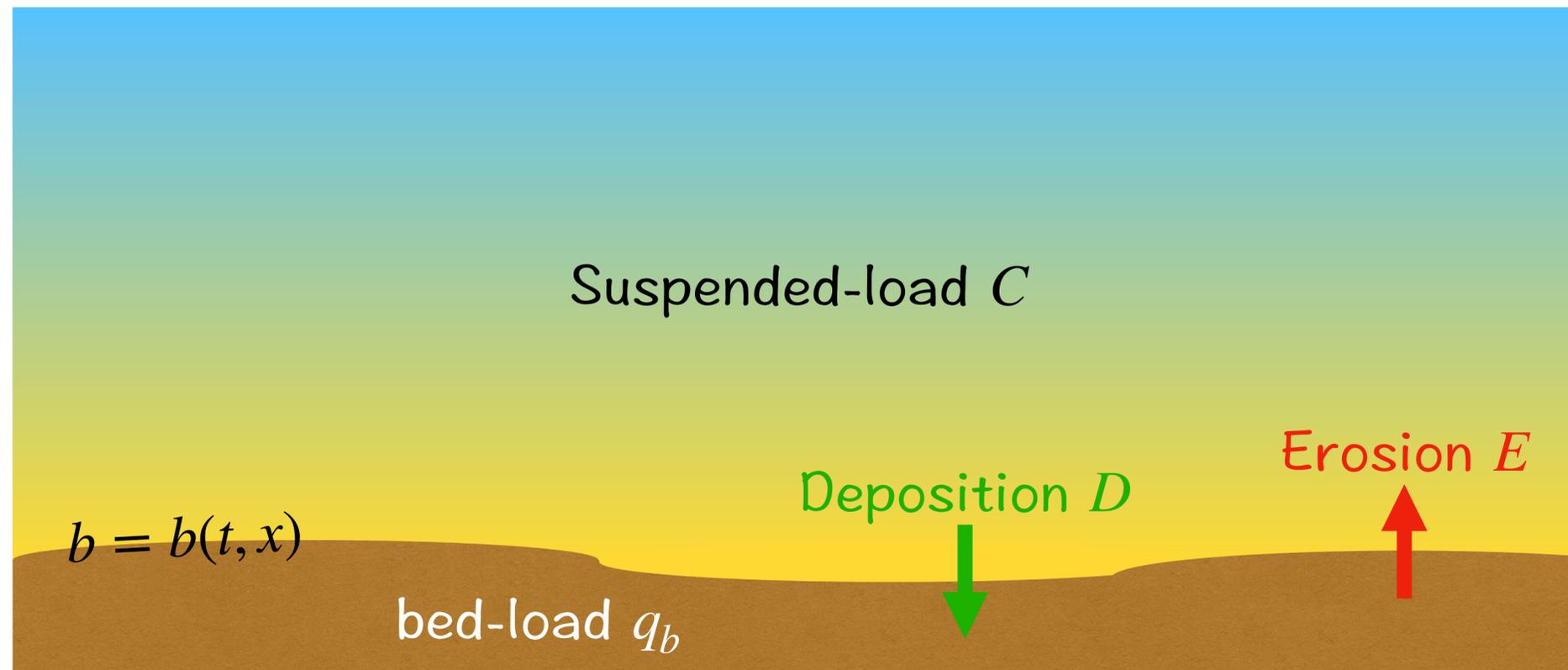
- Highly Empirical



E : sediment erosion rate

D : sediment deposition rate





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Numerical scheme & challenges

Same scheme for hydrodynamic equations: IMEX ARS2(2,2,2)

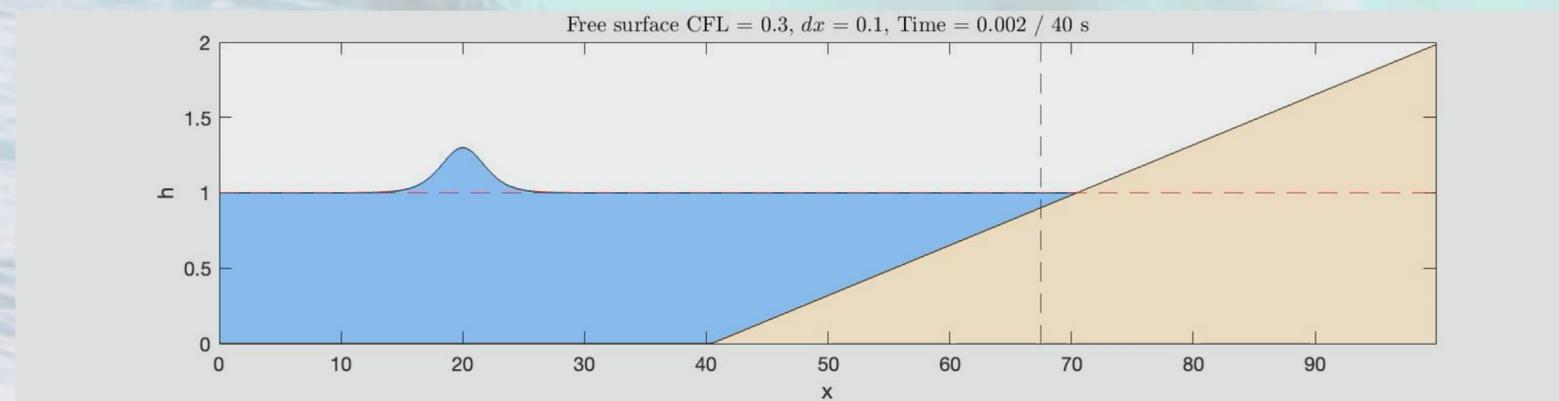
Hydrodynamic equation + equation of C

The non-oscillatory central (NOC) differencing schemes (V. Marieu, **2007**; T. Nagel, **2014**)

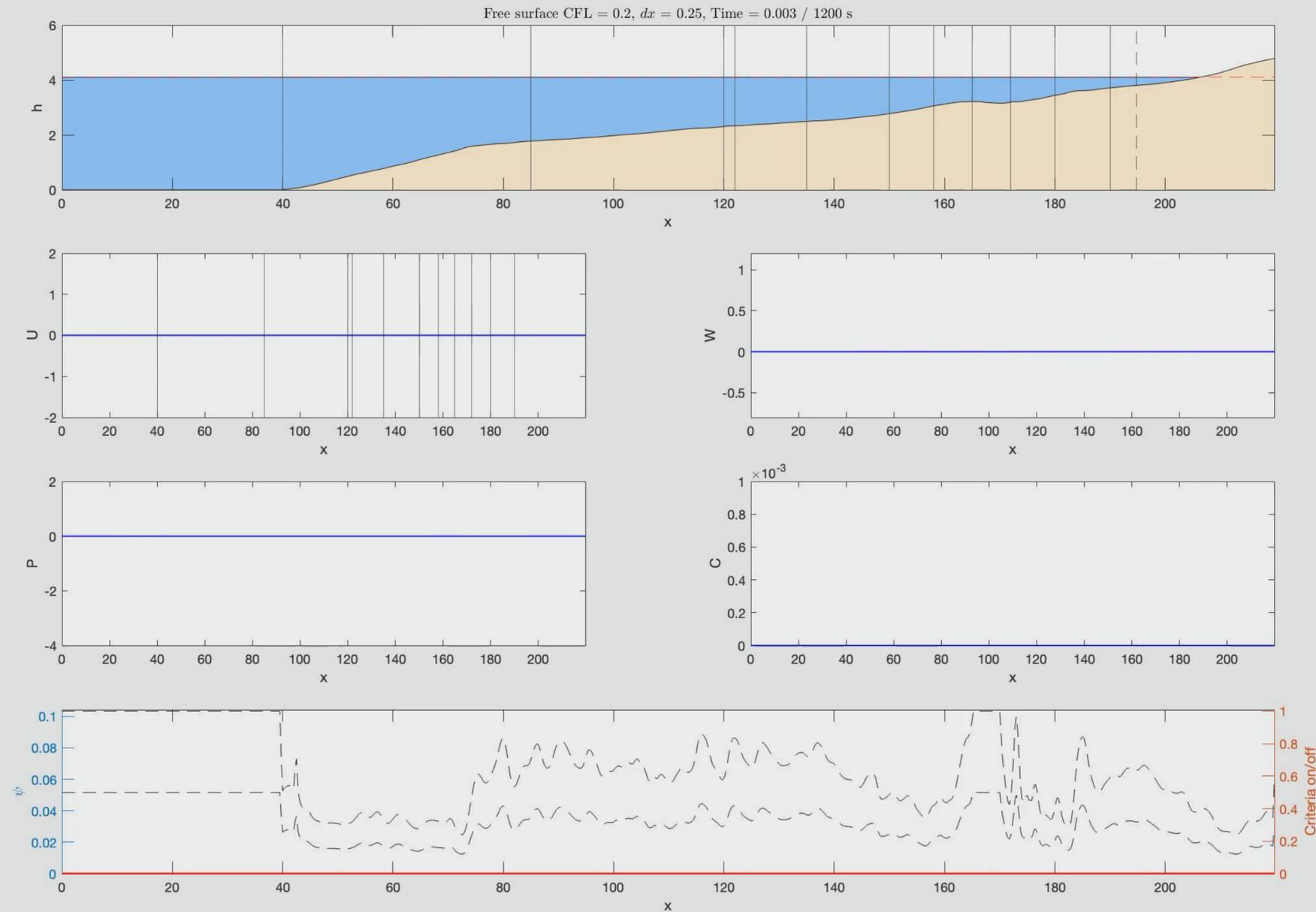
Bed evolution equation

Numerical challenges:

1. The generation of irregular wave trains
2. Wet-dry interface



Numerical scheme & challenges

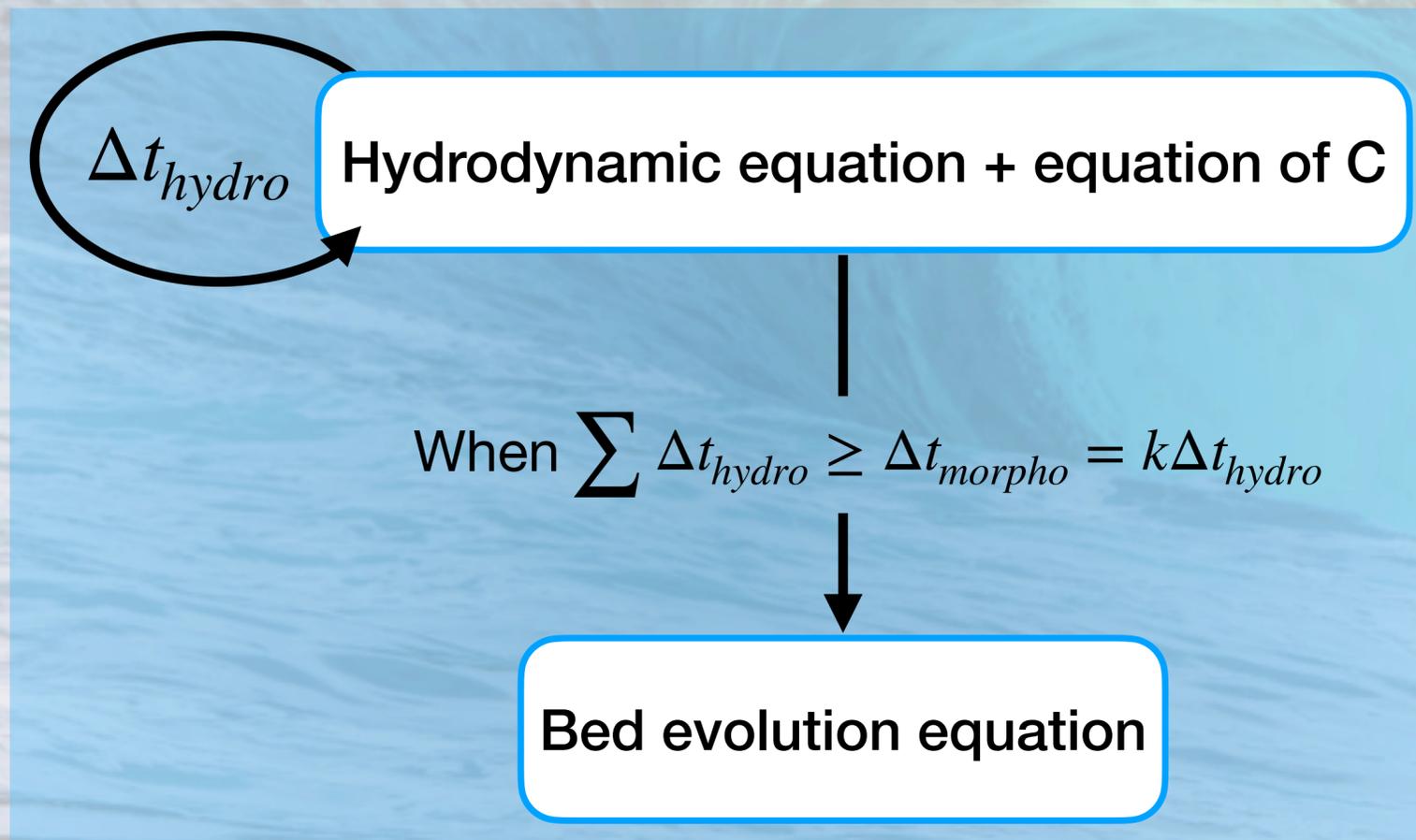


Different time scale

Morphodynamic evolution is much slower than the hydrodynamic processes

→ Assign two different time steps

Only update the bed evolution equation after multiple hydrodynamic time steps



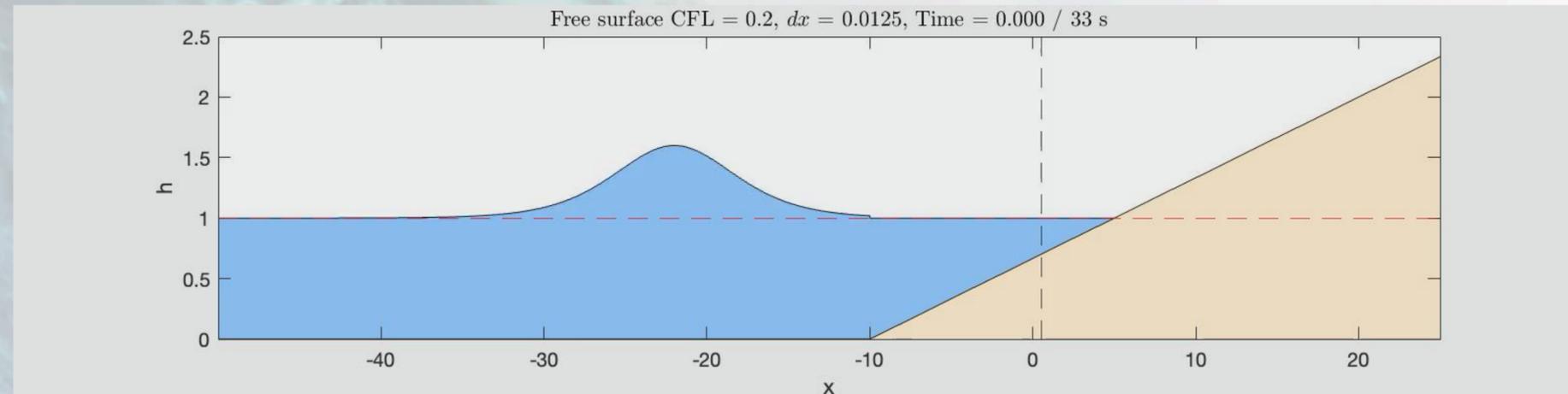
In the case of wave train: **Latteux, 1995**

$$\frac{\partial b}{\partial t} + f_m \frac{\partial q_b}{\partial x} = f_m (D - E)$$

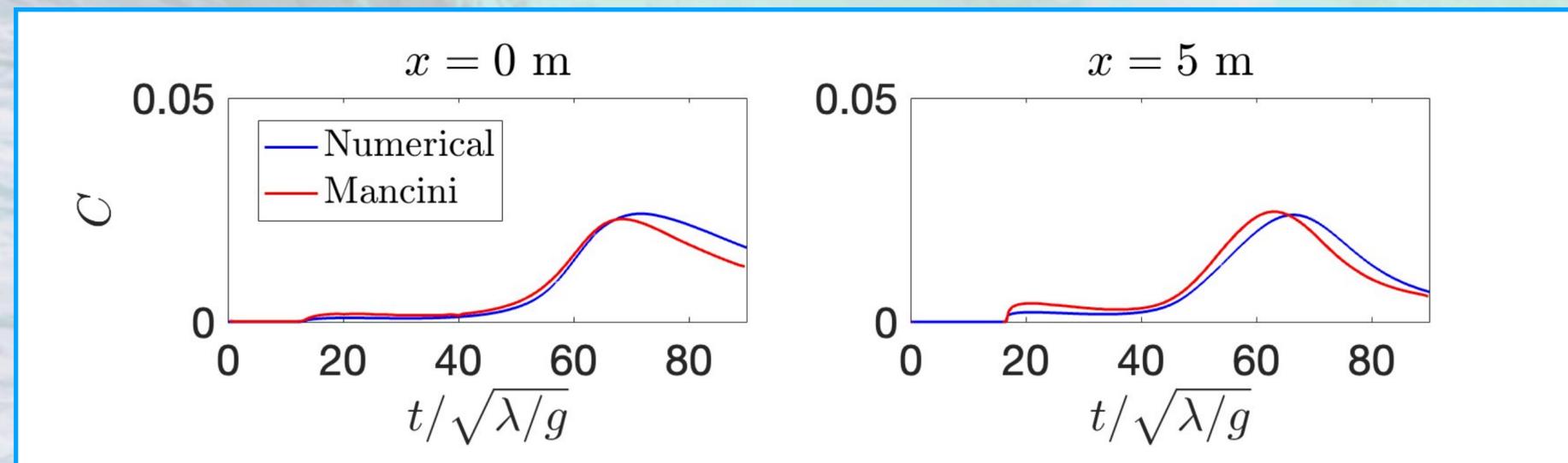
- Simulate f_m successive tides with 1 tide

Solitary wave run-up (Zhu & Dodd, 2015)

Model: NSW equation + equation of C + Exner equation

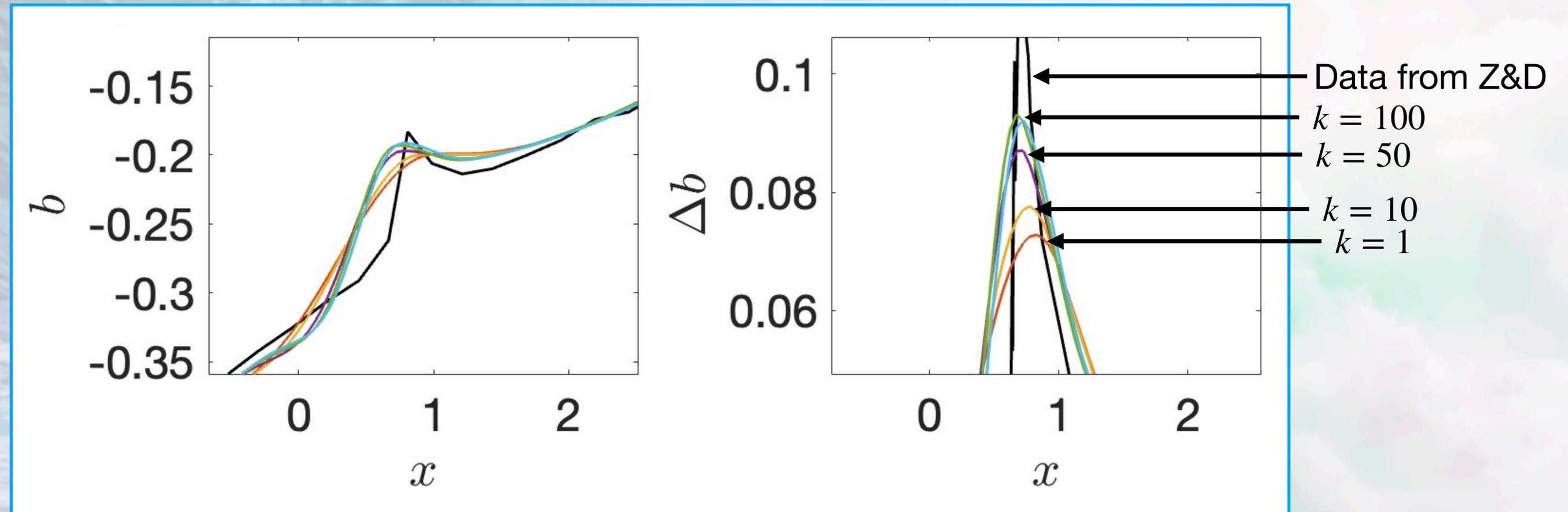


Time series comparison of C at $x = 0$ m and $x = 5$ m with Mancini, 2020



Bed profile comparison

Final bed profile with different choice of k



- Update bed less frequently gives a less diffusive result
- Choice of k should ensure the stability condition of the Exner equation

Outline

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Link with wave breaking

The sediment erosion rate

$$E = \begin{cases} E_0(1 - n_p) \left(\frac{|\tau_b| - \tau_{b,cr}}{\tau_{b,cr}} \right), & \text{if } |\tau_b| > \tau_{b,cr} \\ 0, & \text{otherwise} \end{cases}$$

The friction law takes into account the effect of wave-breaking

For TKE model:

$$\tau_b = C |u_b| \sqrt{u_b^2 + \phi^2(x_b) \alpha_{br}^2 k_b}$$

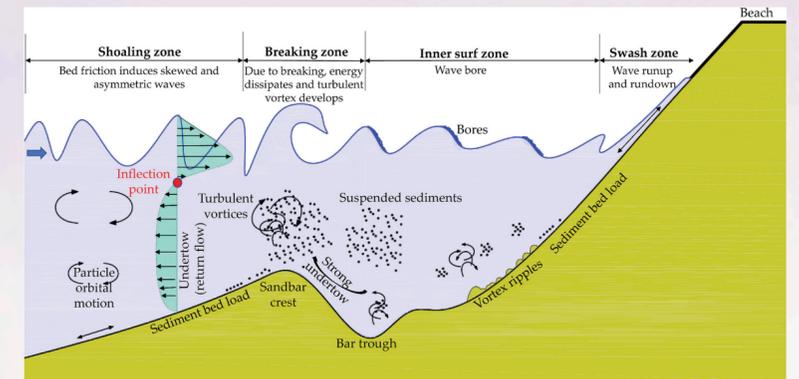
$\phi(x)$: Gaussian function centered around breaking point

k_b : Turbulent kinetic energy

In my model:

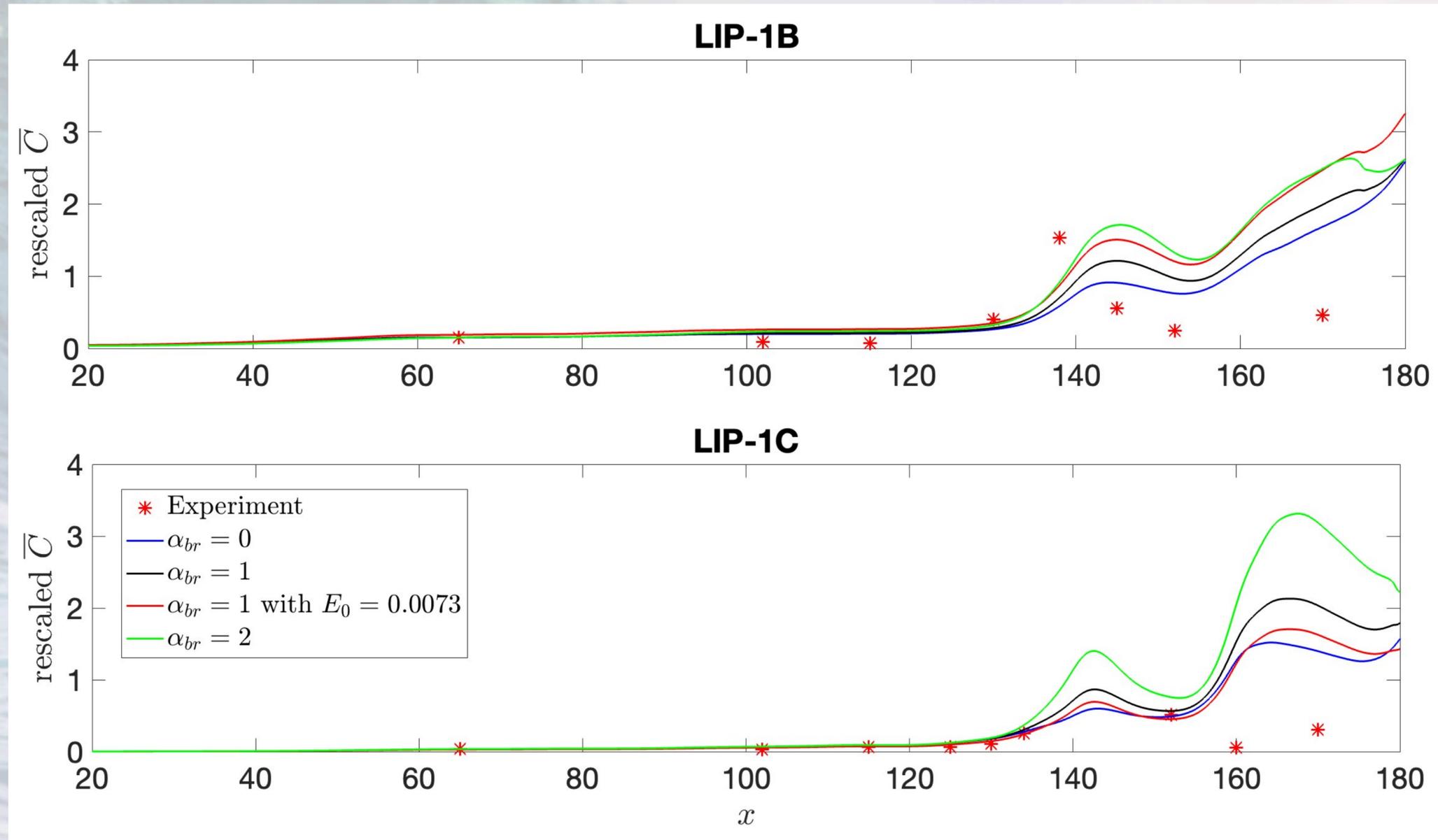
$$\tau_b = C |U| \sqrt{U^2 + \alpha_{br}^2 \varphi}$$

φ : enstrophy



Elsayed, S. M., et al. (2022)

The effect of breaking on suspended load

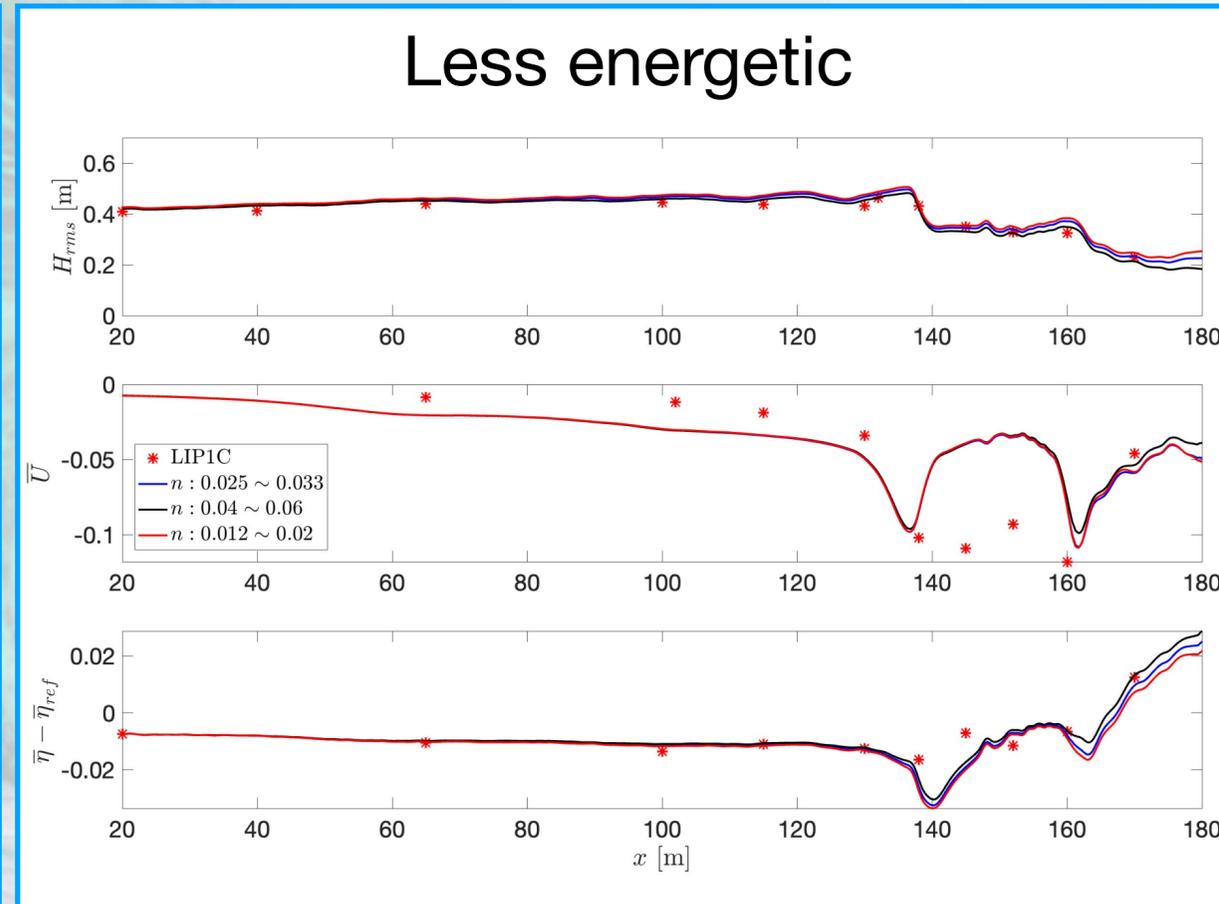
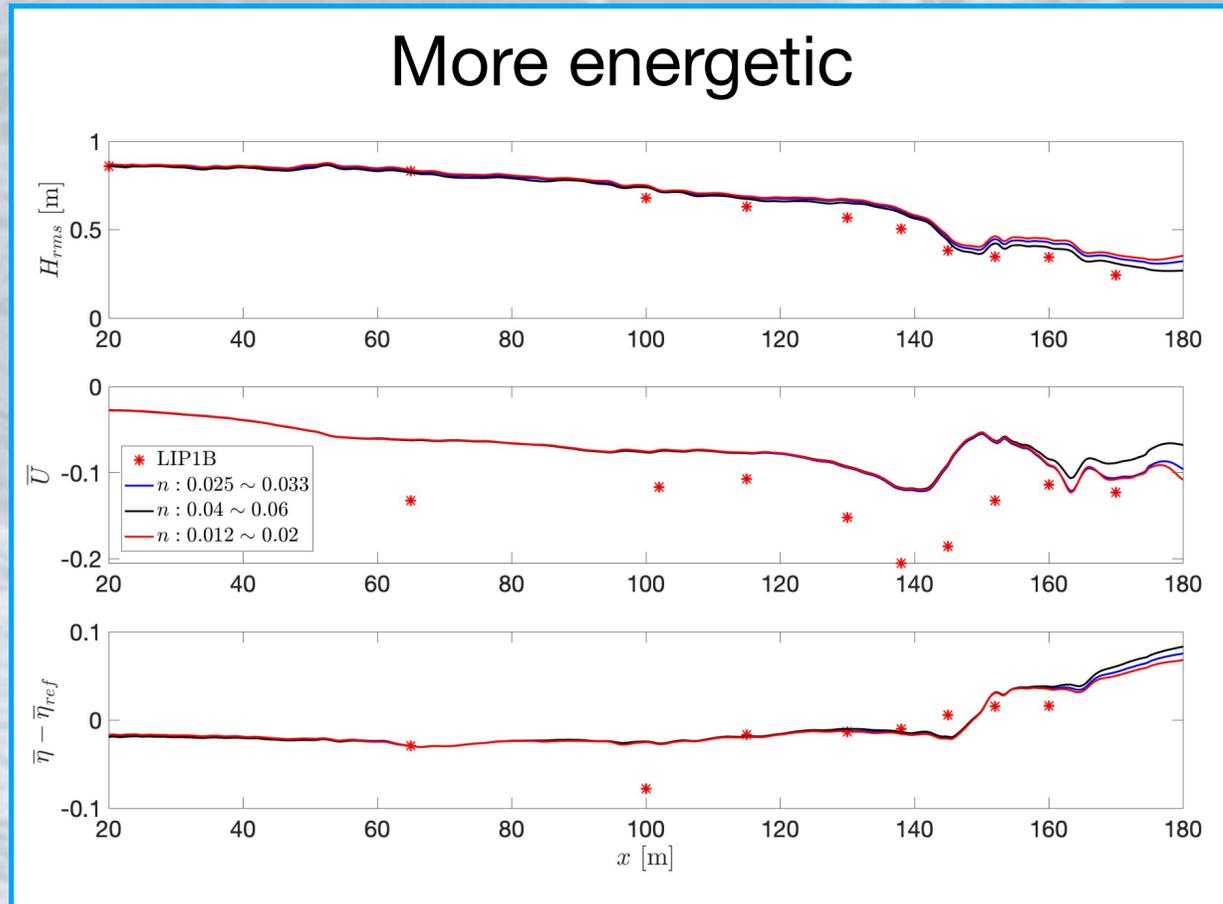


Undertow effect

H_{rms} : root-mean-square of the wave height

\bar{U} : Time-averaged horizontal velocity

$\bar{\eta}$: Time-averaged amplitude



Negative \bar{U} : compensated by undertow effect

Open question & Perspective

Is there a better numerical scheme for bed evolution equation that can bypass the use of k ?

Perspectives

- Implementation in TOLOSA with new numerical scheme developed by Richard & Duran, **2024** for hydrodynamic model
- Bed evolution in the LIP experiment to validate the model's capability in capturing sandbar migration.
- Systematic derivation of the sediment transport equations



Merci de votre attention